



Fig.2B

If station B is responding to another station (Station C) station A reads station B's path loss (from Bs header) to station C and uses his historical "slow" average path loss diffferential to B to calculate pathloss from B to C calibrated with respect to A.

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Station A uses the transmit power used by B in response to C in conjunction with the pathloss declared by B to C to give an indication of the noise at C- if A cannot hear C.

If station B is probing and not responding to any other station -

If station B is responding to A station A reads station Bs calculated path loss to station A in station Bs header pathloss from B to A.

Station A compares his calculated path loss to to that read from B and calculates a differential and uses the differential to update his " average path loss diffferential to B"

Station A uses his measured path loss to B and his "average path loss diffferential to B" to calculate the rate of change of pathloss from B to A from the time A originally transmitted till B responded - used to derive "medium" rate of change of path loss.





Station A uses his measured path loss to B and the rate of change of this path loss during B's transmission to calculate pathloss from B to A and "fast" path loss variation from B to A - taking into account the correction factor -" average path loss diffferential to B"

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Station A uses his calculated pathloss from B to A and updates his database and calculates a "slow" rate of change of pathloss based on past records - used to determine intermediate pathloss variation.

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Station A uses the noise level declared by B to update his database and calculates a "slow" rate of change of noise based on past records - used to determine intermediate noise variation.



Fig.2D

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Station A uses calculated pathloss from B to A in conjunction with station B local noise (from Bs header) to calculate transmit power required to reach B - taking into account the rate of change of pathloss and noise from database both "fast" and "medium".

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If the measured data indicates a "min. imum" in path loss and/or a "min. imum" in noise floor at B an "opportunity" is identified between A and B.

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If A has data for B as a final destination or a relay - and the "opportunity" identified by A to B is better than any other "opportunity" to any other station at that moment - A decides to transmit to B.

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A choses datarate and packet duration based on the ammount of transmit power available at A and the required signal to noise ratio for different data rates and packet durations at B - taking into account the rate of change of pathloss from A to B and noise at B.

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A examines its transmit data que destined for B as a final destination or relay and "fills" the packet with data segments - were packet size is determined by data rate and duration decided on for the opportunity.

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A receives acknowledgement from B or monitors to hear B transmit data further,

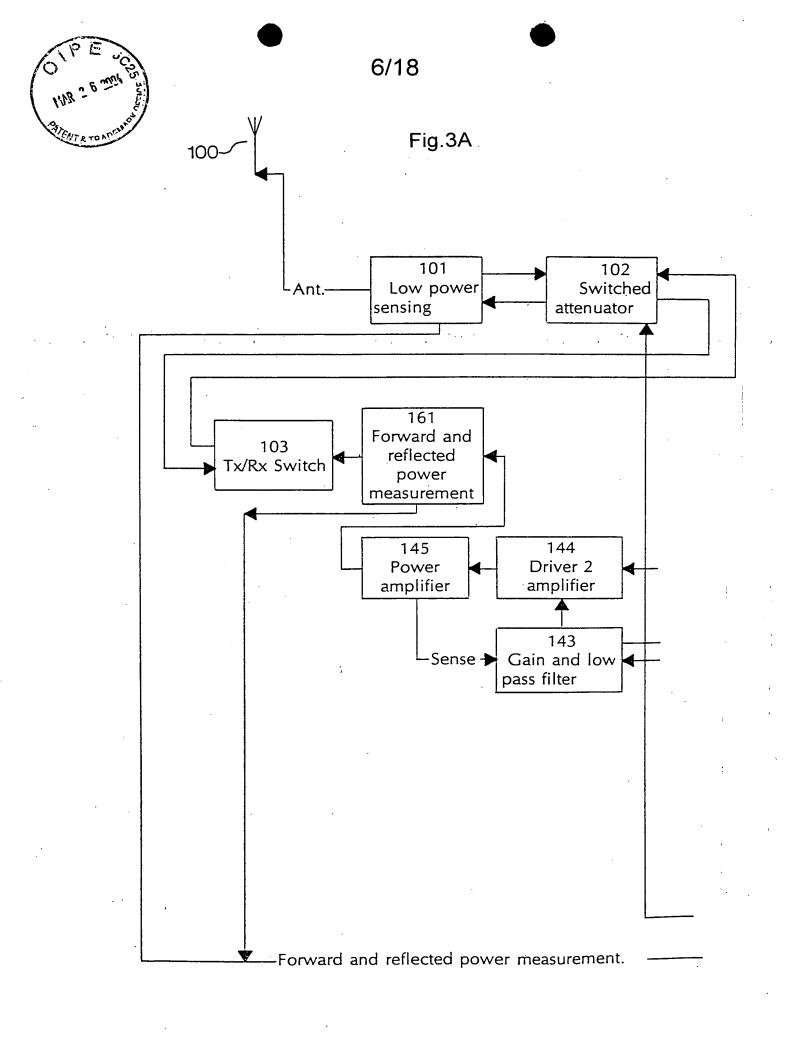
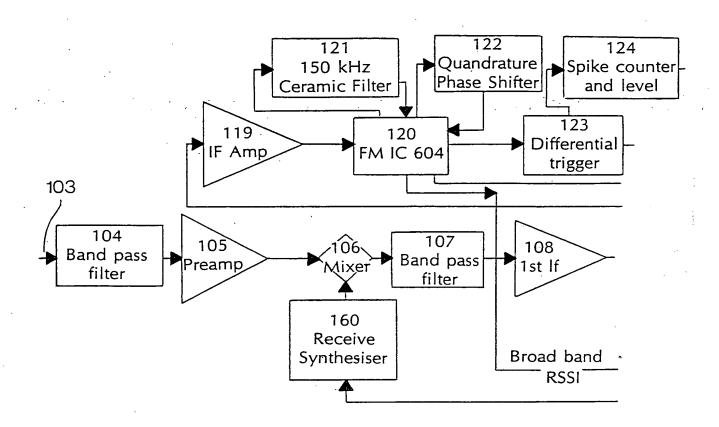




Fig.4A



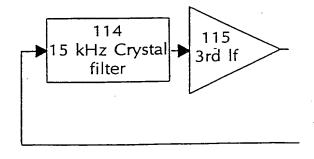




Fig.4B

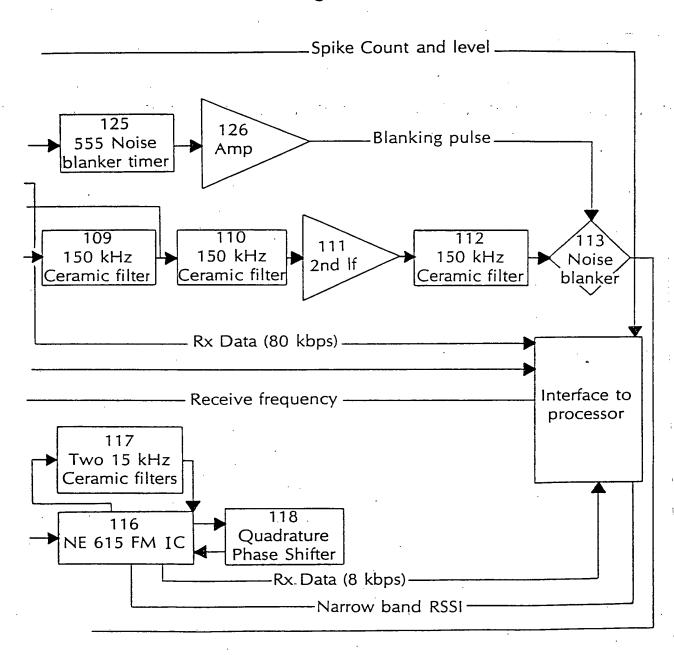




Fig.5A

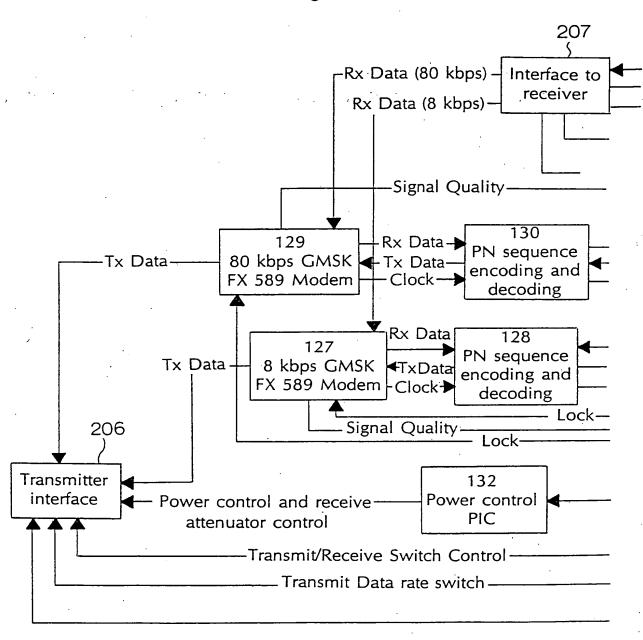
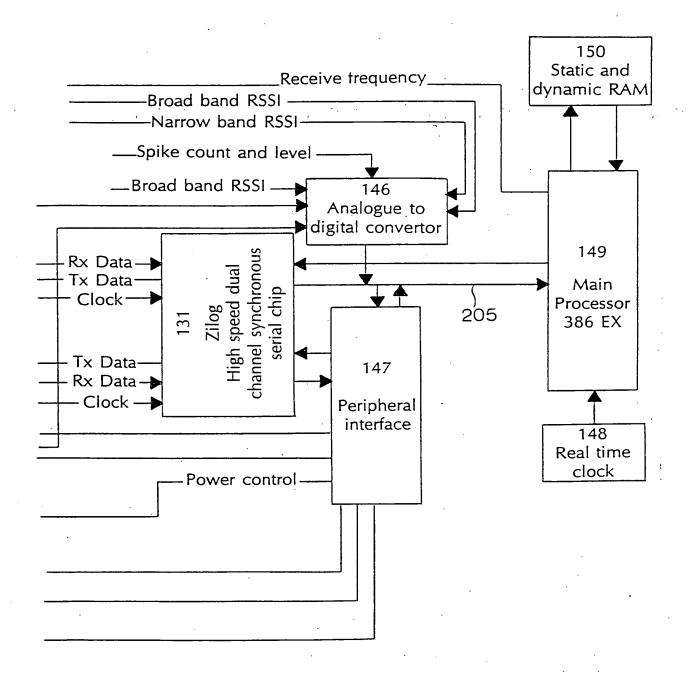




Fig.5B





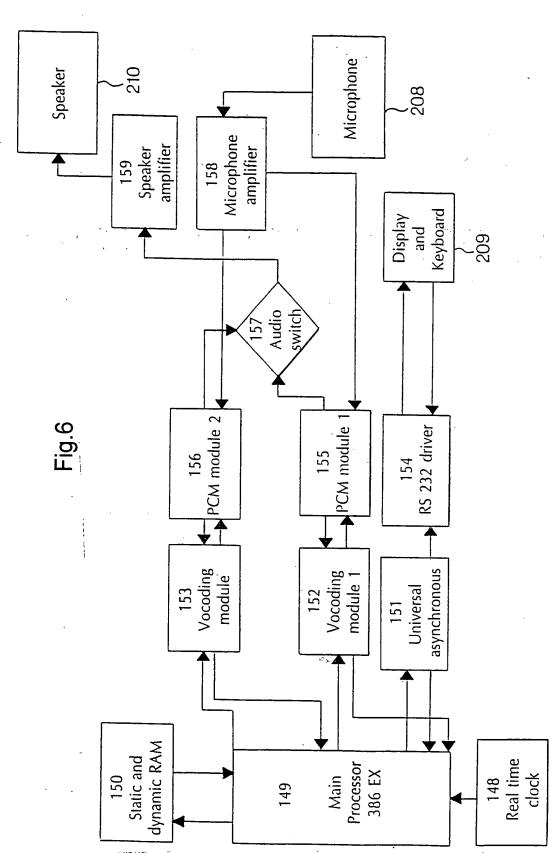
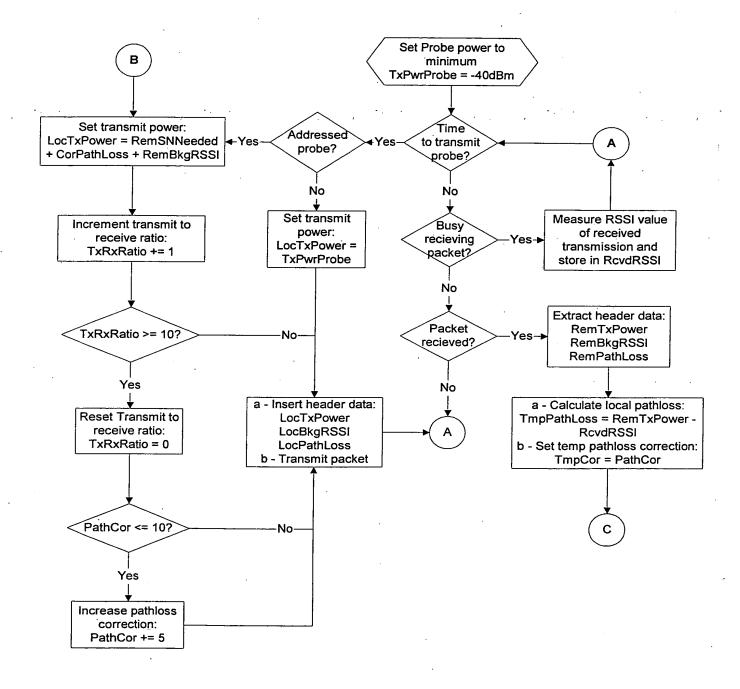




Fig.7A





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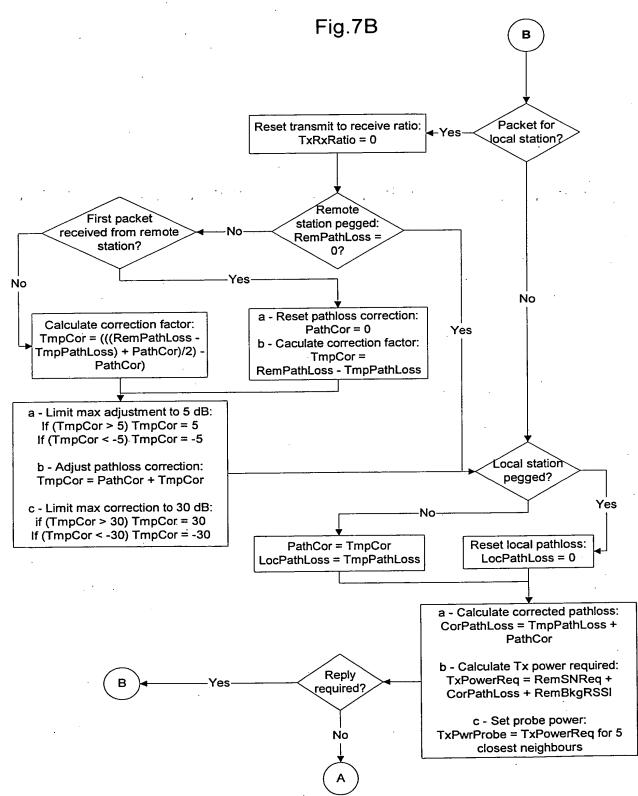




Fig.8A

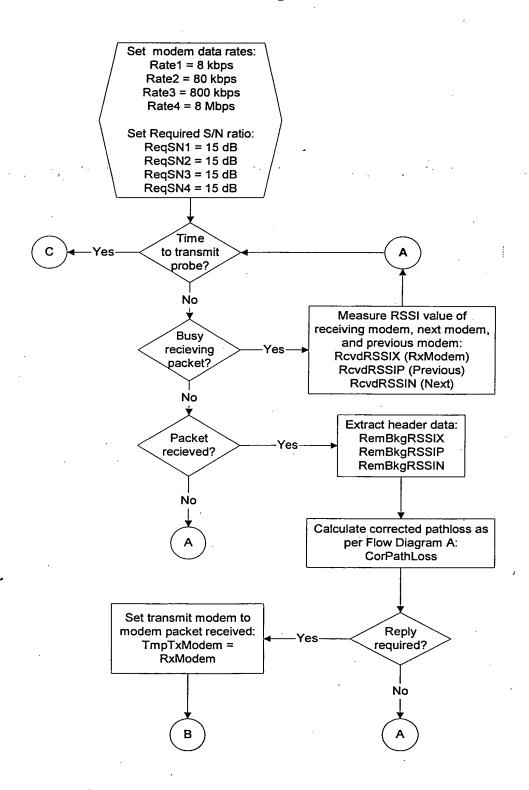
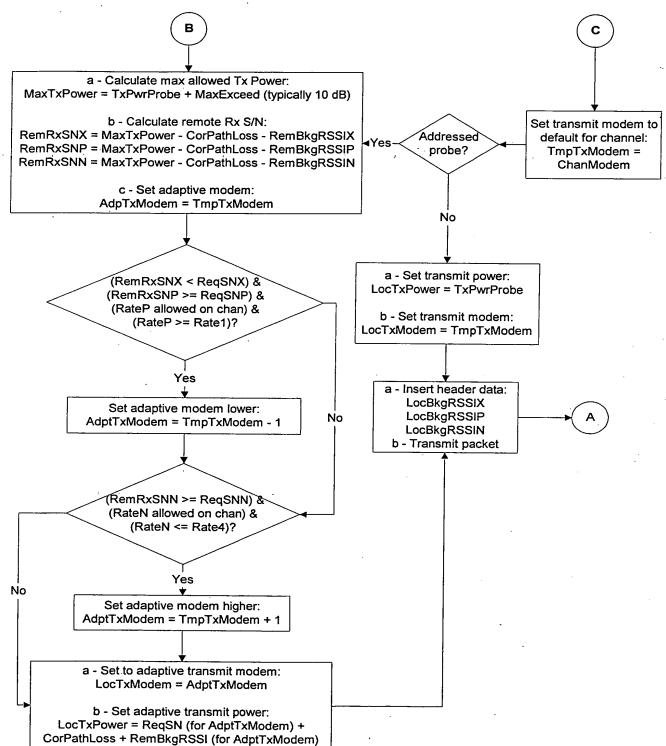




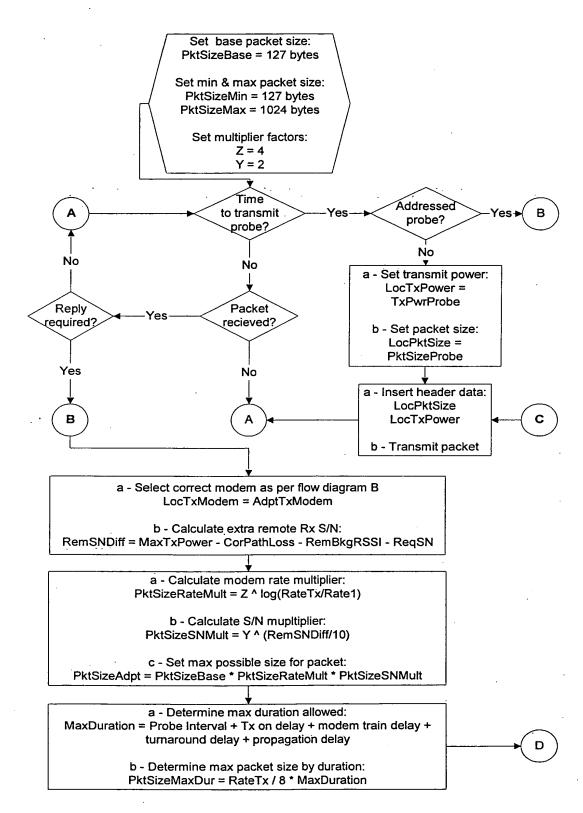
Fig.8B





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Fig.9A





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Fig.9B

